Space-Time Foam Dense Singularities and de Rham Cohomology

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Abstract

In an earlier paper of the authors it was shown that the sheaf theoretically based recently developed abstract differential geometry of the first author can in an easy and natural manner incorporate singularities on arbitrary closed nowhere dense sets in Euclidean spaces, singularities which therefore can have arbitrary large positive Lebesgue measure. As also shown, one can construct in such a singular context a de Rham cohomology, as well as a short exponential sequence, both of which are fundamental in differential geometry. In this paper, these results are significantly strengthened, motivated by the so called *space-time foam structures in general relativity*, where singularities can be *dense*. In fact, this time one can deal with singularities on arbitrary sets, provided that their complementaries are dense, as well. In particular, the cardinal of the set of singularities can be *larger* than that of the nonsingular points.

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'We do not possess any method at all to derive systematically solutions that are free of singularities ... '

Albert Einstein

The Meaning of Relativity

Princeton Univ. Press, 1956, p. 165

'Sensible mathematics involves neglecting a quantity when it turns out to be small - not neglecting it just because it is infinitely great and you do not want it.'

P.A.M. Dirac Directions in Physics H. Hora, J.R. Shepanski, Eds., J. Wiley, 1978, p. 36

1. Basics of Abstract Differential Geometry

1.1. Introduction

There is a longer tradition in enlarging the framework of classical smooth differential geometry in such a way that singularities and various nonsmooth entities need no longer be treated as troublesome exceptions and breakdowns in the otherwise smooth mathematical machinery, but instead, are included in it from the very beginning, and thus can be dealt with in the same unified way, see Souriau [1,2], Geroch [1,2], Geroch & Traschen, Kirillov [1,2], Mostov, Blattner, Heller [1-3], Heller & Sasin [1-3], Gruszczak & Heller, Heller & Mularzynski, Sasin [1,2], Sikorski, Brylinski, Hawking & Penrose, Penrose et.al., Mallios [1-8], Vassiliou [1-5].

The most far reaching approach in this respect is that recently published in Mallios [1], where instead of smooth functions as structure coefficients, one starts with a sheaf of algebras on an arbitrary underlying topological space. Further, one deals with a sequence of sheaves of modules, interrelated with suitable so called differentials, that is, sheaf morphisms which satisfy a Leibniz type rule of product derivative. In this way, one obtains the differential complex and one can recover much of the essence of classical smooth differential geometry, including de Rham cohomology, short exact exponential sequences, characteristic classes (à la Chern-Weil), etc.

In a way, the abstract differential geometry in Mallios [1] recalls what happened in general topolgy at the beginning of the XX-th century, when it was found out that metric concepts, although originated the development of topology, were in fact not necessary, and instead, one could start with the abstract axioms of open, or equivalently, closed sets, as set up by Kuratowski, and still recover much of the important aspects of topology. Similarly, in Mallios [1] it is shown that Calculus, and hence, smooth functions, are in fact not necessary in developing differential geometry. Instead, suitable sheaves of algebras of functions on rather arbitrary topological spaces can be used. And as shown in Mallios & Rosinger, one can go much further, by using sheaves of algebras of generalized functions.

Earlier, in Heller [1], see also Heller [2,3], Heller & Sasin [1-3], Gruszczak & Heller, Heller & Mularzynski, Sasin [1,2], Sikorski, it was shown that in some of such enlarged - but rather more particular - frameworks of differential geometry, one can capture singularities in the underlying topological space which are concentrated on one single *fixed* closed nowhere dense set, a set which however must be on the *boundary* of the space.

In Mallios & Rosinger, with the use of the abstract theory in Mallios [1], and of the nonlinear algebraic theory of generalized functions in Rosinger [1-10], see also Rosinger [11-18], Oberguggenberger & Rosinger, Rosinger & Rudolph, Rosinger & Walus [1,2], it was recently shown that the singularities can now be concentrated on *arbitrary* closed nowhere dense subsets of the underlying topological space, and thus need no longer be in a set fixed in the boundary.

By the way, we should recall that closed nowhere dense subsets in Euclidean spaces can have *arbitrary large* positive Lebesgue measure, Oxtoby.

In this paper, we go far further, by using a recent significant extension of the nonlinear algebraic theory of generalized functions, see Rosinger [14-18]. Indeed, this time the singularities can be on *arbitrary*, including *dense* subsets of the underlying topological space, provided that the complementary of the singularities, that is, the set of nonsingular points, is itself still a *dense* subset. In the case of many topological spaces of interest, in particular, Euclidean spaces, or finite dimensional smooth manifolds, this means

that the singularities can be dense and also have a cardinal *larger* than that of the nonsingular points. Indeed, the singularities can have the cardinal of the continuum, while their complementary, that is, the nonsingular points, need only be countable and dense.

As an example, in the case of the real line \mathbf{R} , the singularities can be all the irrational points, while the nonsingular points can be reduced to the rational ones only.

Interest in *dense* singularities arises, among others, from the study of the so called *space-time foam* in general relativity, see for instance Heller [4], or even Heller & Sasin [3].

For the sake of brevity, here we shall only set up the differential complex and the de Rham cohomology. The construction leading to short exact exponential sheaf sequences will be presented elsewhere.

And now a comment on *commutativity*. All of the mentioned extensions of classical smooth differential geometry, including those in Mallios [1-8], Mallios & Rosinger, as well as in this paper, have so far been done for commutative algebras.

However, since the recent work of Connes, for instance, much interest has focused on noncommutative structures as well. It is important, nevertheless, to point out here three facts in this respect.

First, when it comes to dealing with singularities, and one does so in a differential context, the approach in Connes falls far short from reaching the power even of the much earlier linear distribution theory of Schwartz. Indeed, the only differential type operation in Connes, see [pp 19-28, 287-291], is defined as the commutator with a fixed operator, that is, a Lie type derivation. In this way, it is a rather particular derivation even within a Banach algebra. Not to mention that it cannot come anywhere near to dealing with arbitrary closed nowhere dense singularities, let alone, arbitrary dense singularities which are only restricted by having their complementary dense as well.

Second, the existence of noncommutative theories need not at all mean the loss of interest in, let alone, the abandonment of commutative theories. Indeed, in many important problems the latter turn out to be both more effective and far more simple. Not to mention that, so often, noncommutative theories are such only on their so called 'global' level, while in the last instance of their detailed computations, that is, 'locally', they get reduced to the commutative. Such a reduction is precisely the reason why they may become tractable, as ways are found to have their noncommutative complications reduced to commutative computations, as illustrated quite clearly by matrix theory, for instance. In this connection, one might also refer to N. Bohr's own words, see *Bohr's Correspondence Principle*, according to which 'the description of our measurements of a quantum system must use classical, commutative C-numbers.'

The present paper, as well, can be seen as another illustration of the usefulness, and also relative simplicity - based on a setup of sheaves of algebras - of commutative theories, when it comes to the treatment of by far the largest sets of singularities so far in the literature.

Finally, it should be noted that the differential algebras of generalized functions in Rosinger [1-18], Colombeau, and thus those in Mallios & Rosinger, or also in this paper, can naturally have their *noncommutative* versions as well. Indeed, such versions are obtained as soon as the respective algebras are constructed not starting with real or complex valued functions, but with functions which take values in appropriate noncommutative topological algebras.

1.2. The Differential Triad $(X, \mathcal{A}, \partial)$

It will be useful to recall some basics of the abstract differential geometry introduced in Mallios [1]. Its initial structure is given by an arbitrary topological space X, an associative, commutative and unital sheaf \mathcal{A} of \mathbf{R} -algebras on X, which in the abstract theory is the *structure sheaf of coefficients*, and finally, by a mapping

$$(1.1) \quad \partial: \mathcal{A} \longrightarrow \Omega^1$$

which is the analog of the usual differential operator, and in the general case is only supposed to have the following properties: Ω^1 is any sheaf of \mathcal{A} modules on X, while ∂ is an \mathbf{R} -linear sheaf morphism which satisfies the Leibniz rule of product derivative, namely, for any open $U \subseteq X$ and $\alpha, \beta \in \mathcal{A}(U), \lambda, \mu \in \mathbf{R}$, we have

$$(1.2) \quad \partial(\lambda\alpha + \mu\beta) = \lambda\partial\alpha + \mu\partial\beta$$

$$(1.3) \quad \partial(\alpha\beta) = (\partial\alpha)\beta + \alpha(\partial\beta)$$

where we note that $\mathbf{R} \subseteq \mathcal{A}$, since \mathcal{A} is unital.

We call $(X, \mathcal{A}, \partial)$ the differential triad and recall that in Mallios [1] the notation $(\mathcal{A}, \partial, \Omega)$ was used instead.

We also note that the classical differential geometric setup follows when X is an open subset of \mathbf{R}^n , or it is an n-dimensional manifold, while $\mathcal{A} = \mathcal{C}^{\infty}(X)$ and ∂ is the corresponding usual differential, with Ω^1 being the set of 1-forms.

Given now a differential triad $(X, \mathcal{A}, \partial)$, then for each $n \in \mathbb{N}, n \geq 2$, we can construct the *n*-fold exterior product

$$(1.4) \quad \Omega^n = \bigwedge^n \Omega^1$$

where the exterior product \wedge , and its iterates, are constructed with respect to the underlying sheaf of algebras \mathcal{A} .

At this stage, we need to introduce one further entity, namely, we assume the existence of an \mathbf{R} -linear sheaf morphism

$$(1.5) d^1: \Omega^1 \longrightarrow \Omega^2$$

which satisfies the respective version of the Leibniz rule of product derivative, namely

(1.6)
$$d^1(\alpha s) = \alpha(d^1 s) + (\partial \alpha) \wedge s$$

for every $\alpha \in \mathcal{A}(U)$, $s \in \Omega^1(U)$, and open $U \subseteq X$. Also, we require that

$$(1.7) d^1 \circ d^0 = 0$$

where for convenience we denote

$$(1.8) d^0 = \partial$$

Based on the above, we can now construct the R-linear sheaf morphism

$$(1.9) d^2: \Omega^2 \longrightarrow \Omega^3$$

by defining it according to

$$(1.10) d2(s \wedge t) = s \wedge (d1t) + (d1s) \wedge t$$

for $s, t \in \Omega^1(U)$ and any open $U \subseteq X$.

Finally, as a last assumption, we require that d^2 satisfy

$$(1.11) d^2 \circ d^1 = 0$$

Based on the above, we can now construct all the R-linear sheaf morphisms

$$(1.12) d^n: \Omega^n \longrightarrow \Omega^{n+1}, n \in \mathbf{N}, n \ge 3$$

by defining them according to

$$(1.13) d^n(s \wedge t) = (d^{n-1}s) \wedge t + (-1)^{n-1}s \wedge (d^1t)$$

where $s \in \Omega^{n-1}(U), t \in \Omega^1(U)$, and $U \subseteq X$ is open.

1.3. De Rham Complexes

An important fact, which allows the construction of de Rham complexes in the above abstract framework, is that, within the mentioned constructions, we obtain, see Mallios [1, chap. viii, sect. 8]

Lemma 1

The relations hold

$$(1.14) d^3 \circ d^2 = d^4 \circ d^3 = \dots = d^{n+1} \circ d^n = \dots = 0, n \in \mathbb{N}, n \ge 2$$

2. Sheaves of Algebras of Generalized Functions with Dense Singularities, or Space-Time Foam Algebras

2.1. Families of Dense Singularities in Euclidean Spaces.

Let our domain for generalized functions be any nonvoid open subset X of \mathbf{R}^n . We shall consider various families of singularities in X, each such family being given by a corresponding set S of subsets $\Sigma \subset X$, with each such subset Σ describing a possible set of singularities of a certain given

generalized function.

The *largest* family of singularities $\Sigma \subset X$ which we can deal with is given by

$$(2.1) \quad \mathcal{S}_{\mathcal{D}}(X) = \{ \Sigma \subset X \mid X \setminus \Sigma \text{ is dense in } X \}$$

The various families S of singularities $\Sigma \subset X$ which we shall use, will therefore each satisfy the condition $S \subseteq S_{\mathcal{D}}(X)$, see for details Rosinger [14-18]. Among other ones, two such families which will be of interest are the following

(2.2)
$$S_{nd}(X) = \{ \Sigma \subset X \mid \Sigma \text{ is closed and nowhere dense in } X \}$$
 and

(2.3)
$$S_{Baire\ I}(X) = \{ \Sigma \subset X \mid \Sigma \text{ is of first Baire category in } X \}$$

Obviously

$$(2.4) \quad \mathcal{S}_{nd}(X) \subset \mathcal{S}_{Baire\ I}(X) \subset \mathcal{S}_{\mathcal{D}}(X)$$

In Mallios & Rosinger, only singularities Σ in $\mathcal{S}_{nd}(X)$ were considered. Thus, in view of (2.4) alone, it is clear how much more powerful the corresponding results in this paper are, since now we can consider all the singularities in $\mathcal{S}_{Baire\ I}(X)$, and in fact, even in $\mathcal{S}_{\mathcal{D}}(X)$.

2.2. Asymptotically Vanishing Ideals

The construction of the space-time foam algebras, first introduced in Rosinger [14-18], has two basic ingredients involved. First, we take any family S of singularity sets $\Sigma \subset X$, family which satisfies the conditions

$$\forall \ \Sigma \in \mathcal{S} :$$

(2.5)
$$X \setminus \Sigma$$
 is dense in X

and

$$\forall \ \Sigma, \ \Sigma' \in \mathcal{S} \ :$$

$$(2.6) \quad \exists \ \Sigma'' \in \mathcal{S} :$$

$$\Sigma \cup \Sigma' \subset \Sigma''$$

Clearly, we shall have the inclusion $S \subseteq S_D(X)$ for any such family S. Also, it is easy to see that both families $S_{nd}(X)$ and $S_{Baire\ I}(X)$ satisfy conditions (2.5) and (2.6).

Now, as the second ingredient, and so far independently of S above, we take any right directed partial order $L = (\Lambda, \leq)$. In other words, L is such that for each λ , $\lambda' \in \Lambda$, there exists $\lambda'' \in \Lambda$, for which we have λ , $\lambda' \leq \lambda''$. The choice of L may at first appear to be independent of S, yet in certain specific instances the two may be related, with the effect that Λ may have to be large, see for details subsection 2.8. and Rosinger [15, subsection 2.6.].

Although we shall only be interested in singularity sets $\Sigma \in \mathcal{S}_{\mathcal{D}}(X)$, the following ideal can be defined for any $\Sigma \subseteq X$. Indeed, let us denote by

$$(2.7)$$
 $\mathcal{J}_{L,\Sigma}(X)$

the *ideal* in $(\mathcal{C}^{\infty}(X))^{\Lambda}$ of all the sequences of smooth functions indexed by $\lambda \in \Lambda$, namely, $w = (w_{\lambda} \mid \lambda \in \Lambda) \in (\mathcal{C}^{\infty}(X))^{\Lambda}$, sequences which *outside* of the singularity set Σ will satisfy the *asymptotic vanishing* condition

$$\exists \ \lambda \in \Lambda \ :$$

$$(2.8) \qquad \forall \ \mu \in \Lambda, \ \mu \ge \lambda \ :$$

$$\forall \ p \in \mathbf{N}^n \ :$$

 $\forall x \in X \setminus \Sigma$:

$$D^p w_\mu(x) = 0$$

This means that the sequences of smooth functions $w = (w_{\lambda} \mid \lambda \in \Lambda)$ in the ideal $\mathcal{J}_{L,\Sigma}(X)$ will in a way *cover* with their support the singularity set Σ , and at the same time, they vanish outside of it, together with all their partial derivatives.

In this way, the ideal $\mathcal{J}_{L,\Sigma}(X)$ carries in an algebraic manner the information on the singularity set Σ . Therefore, a quotient in which the factorization is made with such ideals may in certain ways do away with singularities, and do so through purely algebraic means, see (2.11), (5.1) below.

We note that the assumption about $L = (\Lambda, \leq)$ being right directed is

used in proving that $\mathcal{J}_{L,\Sigma}(X)$ is indeed an ideal, more precisely that, for $w, w' \in \mathcal{J}_{L,\Sigma}(X)$, we have $w + w' \in \mathcal{J}_{L,\Sigma}(X)$.

Now, it is easy to see that for Σ , $\Sigma' \subseteq X$, we have

$$(2.9) \quad \Sigma \subseteq \Sigma' \implies \mathcal{J}_{L,\Sigma}(X) \subseteq \mathcal{J}_{L,\Sigma'}(X)$$

in this way, in view of (2.6), it follows that

$$(2.10) \quad \mathcal{J}_{L,\mathcal{S}}(X) = \bigcup_{\Sigma \in \mathcal{S}} \mathcal{J}_{L,\Sigma}(X)$$

is also an *ideal* in $(\mathcal{C}^{\infty}(X))^{\Lambda}$.

It is important to note that for suitable choices of the right directed partial orders L, the ideals $\mathcal{J}_{L,\Sigma}(X)$, with $\Sigma \in \mathcal{S}_{\mathcal{D}}(X)$, are nontrivial, that is, they do not collapse to $\{0\}$. Thus in view of (2.10), the same will hold for the ideals $\mathcal{J}_{L,S}(X)$. In Rosinger [15, section 2] further details are presented in the case of general singularity sets $\Sigma \in \mathcal{S}_{\mathcal{D}}(X)$, when the respective right directed partial orders L which give the nontriviality of the ideals $\mathcal{J}_{L,\Sigma}(X)$ prove to be rather large, and in particular, uncountable. In subsection 2.8., we shall show that in the case of the singularity sets Σ in $\mathcal{S}_{nd}(X)$, and in fact, even in $\mathcal{S}_{\delta \ Baire \ I}(X)$ - which, see (2.28) below, is a suitable subset of $\mathcal{S}_{Baire \ I}(X)$ - one can have the ideals $\mathcal{J}_{L,\Sigma}(X)$ nontrivial even for $L = \mathbf{N}$, respectively, for $L = \mathbf{N} \times \mathbf{N}$, that is, with L still countable.

On the other hand, in view of (2.13), (2,15) below, the mentioned ideals cannot become too large either.

2.3. Foam Algebras

In view of the above, for $\Sigma \subseteq X$, we can define the algebra

$$(2.11) B_{L,\Sigma}(X) = (\mathcal{C}^{\infty}(X))^{\Lambda} / \mathcal{J}_{L,\Sigma}(X)$$

However, we shall only be interested in singularity sets $\Sigma \in \mathcal{S}_{\mathcal{D}}(X)$, that is, for which $X \setminus \Sigma$ is dense in X, and in such a case the corresponding algebra $B_{L,\Sigma}(X)$ will be called a *foam algebra*.

2.4. Multi-Foam Algebras

With the given family S of singularities, based on (2.10), we can associate the *multi-foam algebra*

$$(2.12) B_{L,S}(X) = (\mathcal{C}^{\infty}(X))^{\Lambda} / \mathcal{J}_{L,S}(X)$$

2.5. Space-Time Foam Algebras

The foam algebras and the multi-foam algebras introduced above will for the sake of simplicity be called together space-time foam algebras. Clearly, if the family S of singularities consists of one single singularity set $\Sigma \in S_{\mathcal{D}}(X)$, that is, $S = \{ \Sigma \}$, then conditions (2.5), (2.6) are satisfied, and in this particular case the concepts of foam and multi-foam algebras are identical, in other words, $B_{L,\{\Sigma\}}(X) = B_{L,\Sigma}(X)$. This means that the concept of multi-foam algebra is more general than that of a foam algebra.

It is clear from their quotient construction that the space-time foam algebras are associative and commutative. However, the above constructions can easily be extended to the case when, instead of real valued smooth functions, we use smooth functions with values in a suitable topological algebra, or even in an arbitrary normed algebra. In such a case the resulting space-time foam algebras will still be associative, but in general they may be noncommutative, depending on the algebras chosen for the ranges of the smooth functions.

2.6. Space-Time Foam Algebras as Algebras of Generalized Functions

The reason why we restrict ourself to singularity sets $\Sigma \in \mathcal{S}_{\mathcal{D}}(X)$, that is, to subsets $\Sigma \subset X$ for which $X \setminus \Sigma$ is dense in X, is due to the implication

(2.13)
$$X \setminus \Sigma$$
 is dense in $X \implies \mathcal{J}_{L,\Sigma}(X) \cap \mathcal{U}^{\infty}_{\Lambda}(X) = \{ 0 \}$

where $\mathcal{U}^{\infty}_{\Lambda}(X)$ denotes the diagonal of the power $(\mathcal{C}^{\infty}(X))^{\Lambda}$, namely, it is the set of all $u(\psi) = (\psi_{\lambda} \mid \lambda \in \Lambda)$, where $\psi_{\lambda} = \psi$, for $\lambda \in \Lambda$, while ψ ranges over $\mathcal{C}^{\infty}(X)$. In this way, we have the algebra isomorphism $\mathcal{C}^{\infty}(X) \ni \psi \longmapsto u(\psi) \in \mathcal{U}^{\infty}_{\Lambda}(X)$. The implication (2.13) results immediately from the asymptotic vanishing condition (2.8), and it means that the ideal $\mathcal{J}_{L,\Sigma}(X)$ is off diagonal. Yet the importance of (2.13) is that, for $\Sigma \in \mathcal{S}_{\mathcal{D}}(X)$, it gives the following algebra embedding of the smooth functions into foam algebras

$$(2.14) \quad \mathcal{C}^{\infty}(X) \ni \psi \longmapsto u(\psi) + \mathcal{J}_{L,\Sigma}(X) \in B_{L,\Sigma}(X)$$

Now in view of (2.10), it is easy to see that (2.13) will yield the *off diagonality* property as well

$$(2.15) \quad \mathcal{J}_{L,\mathcal{S}}(X) \cap \mathcal{U}^{\infty}_{\Lambda}(X) = \{ 0 \}$$

and thus similarly with (2.14), we obtain the algebra embedding of smooth functions into multi-foam algebras

$$(2.16) \quad \mathcal{C}^{\infty}(X) \ni \psi \longmapsto u(\psi) + \mathcal{J}_{L,\mathcal{S}}(X) \in B_{L,\mathcal{S}}(X)$$

The algebra embeddings (2.14), (2.16) mean that the foam and multifoam algebras are in fact algebras of generalized functions. Also they mean that the multi-foam algebras are unital, with the respective unit elements $u(1) + \mathcal{J}_{L,\Sigma}(X)$, $u(1) + \mathcal{J}_{L,S}(X)$.

Further, the asymptotic vanishing condition (2.8) also implies quite obviously that, for $\Sigma \subseteq X$, we have

(2.17)
$$D^p \mathcal{J}_{L,\Sigma}(X) \subseteq \mathcal{J}_{L,\Sigma}(X)$$
, for $p \in \mathbf{N}^n$

where D^p denotes the termwise p-th order partial derivation of sequences of smooth functions, applied to each such sequence in the ideal $\mathcal{J}_{L,\Sigma}(X)$. Then again, in view of (2.10), we obtain

(2.18)
$$D^p \mathcal{J}_{L,\mathcal{S}}(X) \subseteq \mathcal{J}_{L,\mathcal{S}}(X)$$
, for $p \in \mathbf{N}^n$

Now (2.17), (2.18) mean that the foam and multi-foam algebras are in fact differential algebras, namely

(2.19)
$$D^p B_{L,\Sigma}(X) \subseteq B_{L,\Sigma}(X)$$
, for $p \in \mathbf{N}^n$

where $\Sigma \in \mathcal{S}_{\mathcal{D}}(X)$, while we also have

(2.20)
$$D^p B_{L,S}(X) \subseteq B_{L,S}(X)$$
, for $p \in \mathbf{N}^n$

In this way we obtain that the foam and multi-foam algebras are differential algebras of generalized functions.

Also, the multi-foam algebras contain the Schwartz distributions, that is, we have the *linear embeddings* which respect the arbitrary partial derivation of smooth functions

(2.21)
$$\mathcal{D}'(X) \subset B_{L,\Sigma}(X)$$
, for $\Sigma \in \mathcal{S}_{\mathcal{D}}(X)$

$$(2.22) \quad \mathcal{D}'(X) \subset B_{L,\mathcal{S}}(X)$$

Indeed, we can recall the wide ranging purely algebraic characterization of all those quotient type algebras of generalized functions in which one can embed linearly the Schwartz distributions, a characterization first given in 1980, see Rosinger [4, pp. 75-88], Rosinger [5, pp. 306-315], Rosinger [6, pp. 234-244]. According to that characterization - which also contains the Colombeau algebras as a particular case - the necessary and sufficient condition for the existence of the linear embedding (2.21) is precisely the off diagonality condition in (2.13). Similarly, the necessary and sufficient condition for the existence of the linear embedding (2.22) is exactly the off diagonality condition (2.15).

One more property of the foam and multi-foam algebras will prove to be useful. Namely, in view of (2.10) it is clear that, for every $\Sigma \in \mathcal{S}$, we have the inclusion $\mathcal{J}_{L,\Sigma}(X) \subseteq \mathcal{J}_{L,\mathcal{S}}$, and thus we obtain the *surjective algebra homomorphism*

$$(2.23) \quad B_{L,\Sigma}(X) \ni w + \mathcal{J}_{L,\Sigma}(X) \longmapsto w + \mathcal{J}_{L,\mathcal{S}}(X) \in B_{L,\mathcal{S}}(X)$$

As we shall see in the next subsection, (2.23) can naturally be interpreted as meaning that the typical generalized functions in $B_{L,S}(X)$ are more regular than those in $B_{L,\Sigma}(X)$.

2.7. Regularity of Generalized Functions

One natural way to interpret (2.23) in the given context of generalized functions is the following.

Given two spaces of generalized functions E and F, such as for instance

$$(2.24) \quad \mathcal{C}^{\infty}(X) \subset E \subset F$$

then the *larger* the space F, the *less regular* its typical elements can appear to be, when compared with those of E. By the same token, the *smaller* the space E, the *more regular*, compared to those of F, one can consider its typical elements.

This kind of regularity we can call *subset regularity*.

On the other hand, given a *surjective* mapping

$$E \to F$$

it may at first sight appear that one could again consider that the typical elements of F are at least as regular as those of E.

However, as the following simple example shows it, additional arguments may be needed for such a conclusion. Indeed, we clearly have, for instance, the inclusions

$$\mathcal{C}^{\infty}(\mathbf{R}) \subset \mathcal{C}^1(\mathbf{R}) \subset \mathcal{C}^0(\mathbf{R})$$

as well as the surjective linear mapping given by the usual derivative, namely

$$D: \mathcal{C}^1(\mathbf{R}) \longrightarrow \mathcal{C}^0(\mathbf{R})$$

yet it is the elements of $\mathcal{C}^1(\mathbf{R})$ which are considered to be more regular than those of $\mathcal{C}^0(\mathbf{R})$.

In this way, in order to be able to support the argument that in the case of a surjective mapping $E \longrightarrow F$, we can indeed say about F to have more regular elements than those of E, the respective surjective mapping should enjoy certain suitable additional properties. And clearly, such is not the case with the derivative mapping in the counterexample above.

However, if both E and F are quotient vector spaces of the form specified next, and the surjective mapping is the canonical one between them, namely

$$(2.25) \quad E = \mathcal{S}/\mathcal{V} \ni s + \mathcal{V} \longmapsto s + \mathcal{W} \in F = \mathcal{S}/\mathcal{W}$$

where $\mathcal{V} \subseteq \mathcal{W} \subseteq \mathcal{S}$ are vector spaces, then one can see the elements of F as being more regular then those of E, since \mathcal{W} may factor out in F more

than does \mathcal{V} in E.

This kind of regularity we shall call quotient regularity.

In this way, view of (2.23), we can consider that, owing to the given *surjective* algebra homomorphism, the typical elements of the multi-foam algebra $B_{L,S}(X)$ can be seen as being more *quotient regular* than the typical elements of the foam algebra $B_{L,\Sigma}(X)$.

Indeed, the algebra $B_{L,\mathcal{S}}(X)$ is obtained by factoring the same $(\mathcal{C}^{\infty}(X))^{\Lambda}$ as in the case of the algebra $B_{L,\Sigma}(X)$, this time however by the significantly larger ideal $\mathcal{J}_{L,\mathcal{S}}(X)$, an ideal which, unlike any of the individual ideals $\mathcal{J}_{L,\Sigma}(X)$, can simultaneously deal with all the singularity sets $\Sigma \in \mathcal{S}$, some, or in fact, many of which can be dense in X. Further details related to the connection between regularization in the above sense, and on the other hand, properties of stability, generality and exactness of generalized functions and solutions can be found in Rosinger [4-6].

2.8. Nontriviality of Ideals

Let us take any nonvoid singularity set $\Sigma \in \mathcal{S}_{nd}(X)$. Since Σ is closed, we can take a sequence of nonvoid open subsets $Y_l \subset X$, with $l \in \mathbb{N}$, such that $\Sigma = \bigcap_{l \in \mathbb{N}} Y_l$. We can also assume that the Y_l are decreasing in l, since we can replace every Y_l with the finite intersection $\bigcap_{k \leq l} Y_k$. But for each Y_l , Kahn, there exists $\alpha_l \in \mathcal{C}^{\infty}(X)$, such that $\alpha_l = 1$ on Σ , and $\alpha_l = 0$ on $X \setminus Y_l$. Now in view of (2.8) it is easy to check that the resulting sequence of smooth functions on X satisfies

(2.26)
$$\alpha = (\alpha_l \mid l \in \mathbf{N}) \in \mathcal{J}_{\mathbf{N},\Sigma}(X)$$

and clearly, α in not a trivial sequence, since $\phi \neq \Sigma \subseteq \text{supp } \alpha_l$, for $l \in \mathbb{N}$.

We can note, however, that the above argument leading to (2.26) need not necessarily apply to subsets $\Sigma \subset X$ which are not closed, but whose closure is nevertheless nowhere dense in X. In such a case one can use the more general method in Rosinger [15, section 2], which will give nontrivial sequences similar to α above, however, their index sets will no longer be countable.

Let us take now any nonvoid singularity set $\Sigma \in \mathcal{S}_{Baire\ I}(X)$. Then there exists a sequence of closed and nowhere dense subsets $\Sigma_l \subset X$, with $l \in \mathbb{N}$, such that

$$(2.27)$$
 $\Sigma \subset \bigcup_{l \in \mathbb{N}} \Sigma_l$

where the equality need not necessarily hold. Therefore, let us consider the subset of $S_{Baire\ I}(X)$ denoted by

(2.28)
$$\mathcal{S}_{\delta \ Baire \ I}(X)$$

whose elements are all those singularity sets Σ for which we have equality in (2.27). Obviously, we can assume that the Σ_l are increasing in l, since we can replace each Σ_l with the finite union $\bigcup_{k \leq l} \Sigma_k$.

Given now a nonvoid $\Sigma \in \mathcal{S}_{\delta \ Baire \ I}(X)$ and a corresponding representation $\Sigma = \bigcup_{l \in \mathbb{N}} \Sigma_l$, with suitable closed and nowehere dense subsets $\Sigma_l \subseteq X$ which are increasing in l, we can, as above, find for each Σ_l a representation $\Sigma_l = \bigcap_{k \in \mathbb{N}} Y_{lk}$, with nonvoid open subsets $Y_{lk} \subset X$. Further, we can assume that for l, l', k, $k' \in \mathbb{N}$, $l \leq l'$, $k \leq k'$, we have $Y_{lk} \supseteq Y_{l'k'}$, since we can replace every Y_{lk} with the finite intersection $\bigcap_{l' \leq l, k' \leq k} Y_{l'k'}$. Now, for each Y_{lk} , we can find $\alpha_{lk} \in \mathcal{C}^{\infty}(X)$, such that $\alpha_{lk} = 1$ on Σ_l , while $\alpha_{lk} = 0$ on $X \setminus Y_{lk}$.

Let us now take $L = (\Lambda, \leq)$, where $\Lambda = \mathbf{N} \times \mathbf{N}$ and for (l, k), $(l', k') \in \Lambda = \mathbf{N} \times \mathbf{N}$ we set $(l, k) \leq (l', k')$, if and only if $l \leq l'$ and $k \leq k'$. Then (2.8) will easily give

(2.29)
$$\alpha = (\alpha_{lk} \mid (l, k) \in \mathbf{N} \times \mathbf{N}) \in \mathcal{J}_{\mathbf{N} \times \mathbf{N}, \Sigma}(X)$$

And again, α is not a trivial sequence, since $\phi \neq \Sigma \subseteq \bigcup_{l \in \mathbb{N}}$ supp α_{l,k_l} , for every given choice of $k_l \in \mathbb{N}$, with $l \in \mathbb{N}$.

In case our singularity set Σ belongs to $\mathcal{S}_{Baire\ I}(X)$ but not to $\mathcal{S}_{\delta\ Baire\ I}(X)$, then the above approach need no longer work. However, we can still apply the mentioned more general method in Rosinger [15, section 2], in order to construct nontrivial sequences in $\mathcal{J}_{L,\Sigma}(X)$ although this time the corresponding index sets Λ may be uncountable.

2.9. Relations between Algebras with the Same Singularities

The above, and especially subsection 2.8., leads to the following question. Let us assume given a certain nonvoid singularity set $\Sigma \in \mathcal{S}_{\mathcal{D}}(X)$. If we now consider two right directed partial orders $L = (\Lambda, \leq)$ and $L' = (\Lambda', \leq)$, is there then any relevant relationship between the corresponding two foam algebras

$$(2.30)$$
 $B_{L,\Sigma}(X)$ and $B_{L',\Sigma}(X)$?

A rather simple positive answer can be given in the following particular case. Let us assume that Λ is a *cofinal* subset of Λ' , that is, the partial order on Λ is induced by that on Λ' , and in addition, we also have satisfied the condition

$$\forall \lambda' \in \Lambda'$$
:

$$(2.31)$$
 $\exists \lambda \in \Lambda :$

$$\lambda' < \lambda$$

Then considering the surjective algebra homomorphism

$$(\mathcal{C}^{\infty}(X))^{\Lambda'} \ni s' = (s'_{\lambda'} \mid \lambda' \in \Lambda') \stackrel{\rho}{\longmapsto}$$

$$(2.32)$$

$$s = (s'_{\lambda'} \mid \lambda' \in \Lambda) \in (\mathcal{C}^{\infty}(X))^{\Lambda}$$

and based on (2.8), one can easily note the property

$$(2.33) \quad \rho \, \mathcal{J}_{\Lambda',\Sigma}(X) \subseteq \, \mathcal{J}_{\Lambda,\Sigma}(X)$$

In this way, one can obtain the *surjective* algebra homomorphism of foam algebras, given by

$$(2.34) \quad B_{\Lambda',\Sigma}(X) \ni s' + \mathcal{J}_{\Lambda',\Sigma}(X) \stackrel{\rho}{\longmapsto} \rho \ s' + \mathcal{J}_{\Lambda,\Sigma}(X) \in B_{\Lambda,\Sigma}(X)$$

In the terms of the interpretation in subsection 2.7., the meaning of (2.34) is that the foam algebra $B_{\Lambda,\Sigma}(X)$ has its typical generalized functions more regular than those of $B_{\Lambda',\Sigma}(X)$. Thus in such terms, foam algebras which correspond to a smaller cofinal partial order L, can be seen as more regular. However, there may be many other kind of relationships between two partial orders L and L', such as for instace in the case of \mathbf{N} in (2.26), and $\mathbf{N} \times \mathbf{N}$ in (2.29). Therefore the problem in (2.30) may in general present certain difficulties.

Needless to say, similar results and comments hold in the case of the spacetime foam algebras.

2.10. The Flabby and Fine Sheaf Property

We recall that in the abstract differential geometry in Mallios [1], the structure coefficients - no longer given by smooth functions - are sheaves of algebras. And for cohomological and then differential reasons, it proves to be very profitable for such sheaves (loc.cit.) to be flabby and/or fine. With the space-time foam algebras of generalized functions presented in subsections 2.1. - 2.9., the issue of being fine sheaves should, in principle, not raise difficulties, since these algebras are constructed by using classes of sequences of smooth functions. Also we can recall that many other algebras or spaces of generalized functions in the literature prove to be fine sheaves. However, the issue of flabbiness is a priori not so obvious. And it is even less so, if we recall that most of the familiar spaces of generalized functions - and that includes the Scwartz distributions and the Colombeau algebras, among others - fail to be flabby sheaves. Moreover, their lack of flabbiness is quite closely related to a number of deficiencies, as shown for instance in Kaneko.

Fortunately, as with the algebras of generalized functions used in Mallios & Rosinger, which could deal with arbitrary closed nowehere dense singularities, so with the space-time foam algebras used in this paper, which can deal with the much large class of dense singularities in $\mathcal{S}_{\mathcal{D}}(X)$, they prove to be flabby sheaves, as well.

Let us first define a large class of space-time foam algebras $B_{L,S}(X)$ on nonvoid open subsets $X \subseteq \mathbb{R}^n$, each of which will, in Lemma 2 next, prove to have a *fine sheaf* structure. From the proof it will also follow that the respective algebras are *flabby sheaves* as well, in case they satisfy a further rather natural condition. This class contains the nowehre dense algebras, and thus the result presented here is a significant extension of the similar recent result in Mallios & Rosinger [Lemma 2], which was fundamental for that paper.

Given a family S of singularity sets $\Sigma \subset X$ for which the conditions (2.5), (2.6) hold, we call that family *locally finitely additive*, if and only if it satisfies also the condition:

For any sequence of singularity sets $\Sigma_l \in \mathcal{S}$, with $l \in \mathbb{N}$, if we take $\Sigma = \bigcup_{l \in \mathbb{N}} \Sigma_l$, then for every nonvoid open subset $U \subseteq X$, we have $\Sigma \cap U \in \mathcal{S}|_U$, whenever

$$\forall x \in U :$$

 $(2.35) \quad \exists \ \Delta \subseteq U, \ \Delta \text{ neighbourhood of } x :$

$$\{ l \in \mathbb{N} \mid \Sigma_l \cap \Delta \neq \phi \}$$
 is a finite set of indices

It is easy to verify that, see (2.2), (2.3), the families of singularities $S_{nd}(X)$ and $S_{Baire\ I}(X)$ are both locally finitely additive.

Indeed, $S_{Baire\ I}(X)$ is trivially so, since any countable union of first Baire category sets is still of first Baire category. As far as $S_{nd}(X)$ is concerned, it suffices to note two facts. First, a subset of a topological space is closed and nowehre dense, if and only if it is *locally*so, that is, in the neighbourhood of evey point. Second, a finite union of closed nowhere dense sets is again closed and nowhere dense.

Let us also note that $S_{nd}(X)$ and $S_{Baire\ I}(X)$ are among those classes of singularities S which for every nonvoid open subset $U \subseteq X$, satisfy the condition

$$(2.36) \quad \mathcal{S}|_{U} \subseteq \mathcal{S}$$

where we defined the restriction $S|_U$ of S to U, according to

$$(2.37) \quad \mathcal{S}|_{U} = \{ \Sigma \cap U \mid \Sigma \in \mathcal{S} \}$$

We shall use the concept of *sheaf* as is defined by its *sections*, see Bredon, or Mallios [1], Oberguggenberger & Rosinger, Mallios & Rosinger. In particular, we shall deal with *restriction* mappings to nonvoid open subsets $U \subseteq X$.

Let us assume given a family S of singularities which satisfies the conditions (2.5), (2.6). Then it is clear that for every nonvoid open subset $U \subseteq X$, the restriction $S|_U$ of S to U will also satisfy (2.5), (2.6), this time on U.

Let us now be given any right directed partial order $L = (\Lambda, \leq)$. Then the restriction to nonvoid open subsets $U \subseteq X$ of the space-time foam algebra $B_{L,S}(X)$ is the family of space-time foam algebras

(2.38)
$$\mathcal{B}_{L,\mathcal{S},X} = (B_{L,\mathcal{S}|_{U}}(U) \mid U \subseteq X, U \text{ nonvoid open })$$

a relation which follows easily, if we take into account (2.37), and the fact that

(2.39)
$$B_{L,S}(X)|_{U} = B_{L,S|_{U}}(U)$$

which is a direct consequence of (2.12), (2.10), as well as of the obvious relation, see (2.8)

(2.40)
$$\mathcal{J}_{L,\Sigma}(X)|_{U} = \mathcal{J}_{L,\Sigma\cap U}(U), \text{ for } \Sigma \subseteq X$$

We can also note that in the case $\Sigma \cap U = \phi$, the ideal $\mathcal{J}_{L,\phi}(U)$, and thus the algebra $B_{L,\phi}(U)$ are still well defined, as long as U is open and nonvoid, see (2.8), (2.10), (2.12).

Lemma 2

Given on a nonvoid open subset $X \subseteq \mathbf{R}^n$ any family of singularities \mathcal{S} which is locally finitely additive.

Then for every right directed partial order $L = (\Lambda, \leq)$, the family of spacetime foam algebras, see (2.38)

(2.41)
$$\mathcal{B}_{L,\mathcal{S},X} = (B_{L,\mathcal{S}|U}(U) \mid U \subseteq X, U \text{ nonvoid open })$$
 is a fine sheaf on X .

If in addition S has the property

$$(2.42) \quad \forall \ \Sigma \in \mathcal{S}, \ \ U \subseteq X, \ \ U \text{ nonvoid open}, \quad \Gamma \in \mathcal{S}_{nd}(U) :$$

$$(\Sigma \cap U) \cup \Gamma \in \mathcal{S}|_{U}$$

and **N** is, see subsection 2.9., cofinal in Λ , then $\mathcal{B}_{L,S,X}$ in (2.41) is also a flabby sheaf on X.

Proof. See Appendix.

Note 1

The classes of singularities $S_{nd}(X)$ and $S_{Baire\ I}(X)$ satisfy the conditions in Lemma 2 above.

Note 2

If we consider $\mathbf{N} \times \mathbf{N}$ with the partial order in subsection 2.8., and we embed \mathbf{N} into $\mathbf{N} \times \mathbf{N}$ through the diagonal mapping $\mathbf{N} \ni l \longmapsto (l, l) \in \mathbf{N} \times \mathbf{N}$, then \mathbf{N} will be *cofinal* in $\mathbf{N} \times \mathbf{N}$. Thus in view of the Lemma 2 and Note 1 above, it follows that

$$\mathcal{B}_{\mathbf{N}\times\mathbf{N},\mathcal{S}_{Baire\ I}(X),X} = (B_{L,\mathcal{S}_{Baire\ I}(X)|_{U}}(U) \mid U \subseteq X, \ U \text{ nonvoid open })$$

is a fine and flabby sheaf.

This result is nontrivial since $S_{Baire\ I}(X)$ contains lots of singularity sets $\Sigma \subseteq X$, which are both dense in X and uncountable. In particular, this result is a significant strengthening of an earlier similar result in Mallios & Rosinger [Lemma 2], where it was only given in the case of the family of singularities $S_{nd}(X)$.

In Rosinger [16] the above Lemma 2 is in fact proved for X any finite dimensional smooth manifold.

Note 3

In the context of flabbiness of spaces of functions or generalized functions, the presence of $\mathcal{S}_{nd}(X)$ in condition (2.42) appears to be quite natural. For instance, as seen in Oberguggenberger & Rosinger [Remark 7.5, pp. 142-146], the class $\mathcal{S}_{nd}(X)$ of closed nowhere dense singularities appears when one constructs the smallest flabby sheaf which contains $\mathcal{C}^{\infty}(X)$ for a nonvoid open subset $X \subseteq \mathbf{R}^n$. The same happens when constructing the smallest flabby sheaf containing $\mathcal{C}^0(X)$.

Note 4

It is useful to note that there are other ways as well than in (2.8) to define ideals which lead to differential algebras of generalized functions with dense singularities. Here we mention in short one such way used recently in Rosinger [18]. Given any family of singularities \mathcal{S} such as in (2.5), (2.6), we associate with it the *ideal* in $(\mathcal{C}^{\infty}(X))^{\mathbf{N}}$ defined by

$$(2.43) \quad \mathcal{J}_{\mathcal{S}}^{f}(X) = \bigcup_{\Sigma \in \mathcal{S}} \mathcal{J}_{\Sigma}^{f}(X)$$

where $\mathcal{J}_{\Sigma}^{f}(X)$ is the ideal in $(\mathcal{C}^{\infty}(X))^{\mathbf{N}}$ of all sequences of smooth functions $w = (w_{\nu}|\nu \in \mathbf{N})$, which satisfy the condition

$$\forall x \in X \setminus \Sigma, l \in \mathbf{N} :$$

$$\exists \nu \in \mathbf{N} :$$

$$(2.44)$$

$$\forall \mu \in \mathbf{N}, \mu \ge \nu, p \in \mathbf{N}^n, |p| \le l :$$

$$D^p W_{\mu}(x) = 0$$

Clearly, the asymptotic vanishing condition in (2.44) is weaker than that in (2.8). Yet as seen in Rosinger [18], the resulting ideals, and consequently, differential algebras of generalized functions can handle a variety of problems related to dense singularities.

3. Differential Geometry on Space-Time Foam Algebras of Generalized Functions

We now show that the *abstract* differential geometry in Mallios [1], presented in short in section 1, can be implemented - as a particular case, which allows *dense* singularities - by using as *structure sheaf of coefficients* the sheaf of space-time foam algebras of generalized functions, see (2.41) in Lemma 2, section 2.

3.1. Space-Time Foam Differential Triads

We construct a large variety of differential triads as follows. We take X any nonvoid open subset of \mathbb{R}^n . Further, we can choose on X in a variety of ways a family of singularities S which satisfies (2.5), (2.6). Once this is done, then through (2.12), (2.41), we are led to the structure sheaf of coefficients given by the corresponding sheaf $\mathcal{B}_{L,S,X}$ of space-time foam differential algebras of generalized functions.

At that stage, according to the abstract theory, we have to choose the third element, namely, ∂ , of the differential triad, see (1.1). For that purpose, first

we define for every nonvoid open $U \subseteq X$ the corresponding $B_{L,\mathcal{S}}(U)$ -module $\Omega^1(U)$, as being the free $B_{L,\mathcal{S}}(U)$ -module of rank n, with free generators $dx_1, dx_2, dx_3, \ldots, dx_n$. In this way, in view of (2.20), the elements of $\Omega^1(U)$ are given by all

$$(3.1) \quad \sum_{i=1}^{n} V_i \ dx_i$$

where $V_i \in B_{L,\mathcal{S}_L}(U)$.

Thus we can define in our specific case the desired third element of the differential triad, namely, the sheaf morphism ∂ in (1.1), and do so according to

(3.2)
$$B_{L,S}(U) \xrightarrow{\partial} \Omega^{1}(U)$$
$$V \longmapsto \sum_{i=1}^{n} (\partial_{i}V) dx_{i}$$

where as usual, ∂_i denotes the partial derivation with respect to the *i*-th independent variable x_i .

The effect of the choice in (3.1), (3.2) is the following easy to prove result

Lemma 3

$$(X, \mathcal{B}_{L,S,X}, \partial)$$
 is a differential triad.

$$\Diamond\Diamond\Diamond$$

Now according to the abstract theory in section 1, we are at the stage where we have to define the **R**-linear sheaf morphism d^1 in (1.5). In view of (3.1), (3.2) and (1.4), for every nonvoid open $U \subseteq X$, we shall take

$$(3.3) \qquad d^1:\Omega^1(U)\longrightarrow \Omega^2(U)=\Omega^1(U)\wedge\Omega^1(U)$$

where

$$(3.4) d^{1}(\sum_{i=1}^{n} V_{i} dx_{i}) = \sum_{i=1}^{n} \sum_{i=1}^{n} (\partial_{j} V_{i}) dx_{j} \wedge dx_{i}$$

Through a direct computation based on (2.18), (2.20), one can verify that, with this definition in (3.3), (3.4), d^1 will indeed satisfy conditions (1.6), (1.7).

Finally, by implementing (1.9) through (1.10), and using the fact that it is true for smooth functions, another direct computation will give (1.11).

Remark 1

Let us recall that in Rosinger [1-13] a large variety, and in fact, infinitely many classes of differential algebras of generalized functions were constructed. Also a wide ranging purely algebraic characterization was given there for those algebras which contain the linear vector space of Schwartz distributions.

Untill more recently, only two particular cases of these classes of algebras have been used in the study of global generalized solutions of linear and nonlinear PDEs. Namely, first was the class of the nowhere dense differential algebras of generalized functions in Rosinger [3-13], while later came the class of algebras considered in Colombeau.

These latter algebras, since they also contain the Schwartz distributions, are, in view of the above mentioned algebraic characterization, by necessity a particular case of the classes of algebras of generalized functions first introduced in Rosinger [1-13].

The Colombeau algebras of generalized functions enjoy a rather simple and direct connection with the Schwartz distributions, and therefore, with a variety of Sobolev spaces. This led to their relative popularity in the study of generalized solutions of PDEs.

Compared however with the nowhere dense differential algebras of generalized functions, let alone with the space-time foam differential algebras of generalized functions used in this paper, the Colombeau algebras suffer from several important limitations. Among them, relevant to this paper, and in general, to abstract differential geometry, is the following. There are growth conditions which the generalized functions must satisfy in the neighbourhood of their singularities. The effect, among others, is that the Colombeau algebras - just as the Schwartz distributions, for instance - do not form a flabby sheaf. In this way, they would not be the appropriate sheaf of structure coefficients even in such a general theory as the abstract differential geometry in Mallios [1]. In particular, owing to the growth conditions they have to satisfy, the Colombeau algebras do not allow exponential short exact sequences to be defined, see Mallios & Rosinger. This indeed constitutes a severe shortcoming for important applications in mathematical physics, for instance, geometric (pre)quantization, as e.g. Weil's integrality theorem, see Mallios [4], or even Mallios [1, chap. viii, sect. 11].

On the other hand, the earlier introduced nowhere dense algebras do not

suffer from any of the above two limitations. Indeed, the nowhere dense algebras allow singularities on arbitrary closed nowhere dense sets, therefore, such singularity sets can have arbitrary large positive Lebesgue measure, Oxtoby. Furthermore, in the nowhere dense algebras there are no any conditions asked on generalized functions in the neighbourhood of their singularities.

In this paper, the use of the space-time foam differential algebras of generalized functions, introduced recently in Rosinger [14-18], brings a further significant enlargement of the possibilities already given by the nowhere dense algebras, and applied in Mallios & Rosinger. Indeed, this time the singularities can be concentrated on arbitrary subsets, including dense ones, provided that their complementary, that is, the set of nonsingular points, is still dense. Furthermore, as already in the case of the nowhere dense algebras, also in the space-time foam algebras, no any kind of condition is asked on the generalized functions in the neighbourhood of their singularities.

Finally, it should be noted that, since one of the major interests in differential geometry, including in its abstract version in Mallios [1-8], comes from general relativity, it is important to have in the respective frameworks strong and general enough results on the existence of solutions for nonlinear PDEs. In this respect, one could already obtain in the framework of the nowehre dense algebras a rather general, and in fact, type independent and global version of the classical Cauchy-Kovalevaskaia theorem, see Rosinger [7-9]. Indeed, one can prove that every analytic nonlinear PDE, with every associated noncharacteristic analytic initial value problem, has a global generalized solution, which is analytic on the whole domain of definition of the respective PDE, except for a closed nowhere dense set, set which can be chosen to have zero Lebesgue measure.

This global type independent existence results is, fortunately, preserved in the case of the space-time foam algebras as well, see Rosinger [14,15]. So far, one could not obtain any kind of similarly general and powerful existence of solutions result in any of the infinitely many other classes of

algebras of generalized functions, including in the Colombeau class.

4. De Rham Cohomology with Dense Singularities

Let us suppose given a nonvoid open subset $X \subseteq \mathbf{R}^n$ and any family \mathcal{S} of singularities on it, see (2.5), (2.6).

The corresponding space-time foam differential triad $(X, \mathcal{B}_{L,S,X}, \partial)$, see Lemma 3, section 3, leads according to section 1, and the general theory in Mallios [1, chap. iii], to the following complex of **R**-linear sheaf morphisms, that is, to the de Rham complex with dense singularities

$$(4.1) \quad 0 \longrightarrow \mathbf{R} \stackrel{\epsilon}{\longrightarrow} \mathcal{B}_{L,\mathcal{S},X} \stackrel{\partial}{\longrightarrow} \Omega^1 \stackrel{d^1}{\longrightarrow} \Omega^2 \stackrel{d^2}{\longrightarrow} \dots$$

And as an extension of the similar result for nowhere dense singularities in Mallios & Rosinger, here we have for dense singularities

Theorem 1

The de Rham complex (4.1) is exact, namely,

$$(4.2) \quad \ker d^{n+1} = \operatorname{im} d^n, \quad n \in \mathbf{N}$$

where we denoted, see (1.8), $d^0 = \partial$.

Proof. We note that (4.2) is equivalent with the Poincare Lemma in the abstract differential geometry which corresponds to $\mathcal{B}_{L,S,X}$, or more precisely, to the space-time foam differential triad $(X, \mathcal{B}_{L,S,X}, \partial)$, see Mallios [1]. This means that, locally, every closed differential form is exact. In this way, the exactness of (4.1) can be checked 'fiberwise', that is, through the use of (2.18), (2.20), in other words, by reducing it to the classical case of smooth functions.

As X is a nonvoid open subset of \mathbf{R}^n , it follows that X is Hausdorff and paracompact. And in view of Lemma 2, section 2, $\mathcal{B}_{L,\mathcal{S},X}$ is a fine sheaf on X, thus the same holds for all Ω^{n+1} , with $n \in \mathbf{N}$, see Mallios [1, chap. iii, (8.56)].



Now, in the terms of Mallios [1, chap. iii, (8.24)], one obtains

Corollary 1

The complex (4.1) provides a fine, hence, a Γ_X -acyclic resolution of the constant sheaf \mathbf{R} .



Further, if we set $\Omega^0 = \mathcal{B}_{LS,X}$, and for brevity denote by

$$(4.3) \quad (\Omega_{L,\mathcal{S},X}^*)$$

the complex in (4.1), then we can define the *cohomology algebra* $H_{L,S,X}^*$ of (4.3). In this case, the *abstract de Rham theorem*, see Mallios [1, chap iii, (3.25), or even (3.8)], becomes the relation

(4.4)
$$H^*(X, \mathbf{R}) = H^*_{deRham}(X) = H^*_{L,S,X}$$

which means that

the usual singular or \check{C} ech cohomology of X, as well as the standard de Rham cohomology of X, computed in

(4.5) terms of the usual smooth functions and forms on X, can now equally be computed according to the last, and highly singular term in (4.4).

That is, all the mentioned cohomologies of X, being actually functorially isomorphic, given that, by our hypothesis, X is paracompact and Hausdorff, see Mallios [1, chap. iii, (8.11)], they can now be computed through generalized functions, which can have singularities on arbitrary dense subsets in X, provided that the complementary of the singularities is also dense in X.

Now, the conclusion in (4.5) has implementations not only in mathematical physics, where it opens the way to dealing with a large class of new and enlarged singularities. Indeed, it also has implications of a more purely mathematical significance, due to its potential applicability in studying topology and differential geometry of several types of nonsmooth spaces, and do so through cohomological methods of standard differential geometric character, see for example Milnor classifying spaces, simplicial complexes, etc., and also Mostow, along with Rosinger [12], as well as Mallios [1, chap. xi, sect. 12, in particular, (12.27)].

Similarly with Mallios & Rosinger, with the consideration of the short exact exponential sheaf sequence associated with (4.1) or (4.3), one can obtain further extensions of classical results in cohomology.

As an example of this type of results, one can refer to the following abelian $group\ isomorphism$, see also (2.38), (2.41)

$$(4.6) H^1(X, (\mathcal{C}_X^{\infty})^{\bullet}) = H^2(X, \mathbf{Z}) = H^1(X, \mathcal{B}_{L, \mathcal{S}, X}^{\bullet})$$

being of a purely geometrical-physical character. Indeed, in geometric terms (4.6) means that any smooth \mathbf{R} -line bundle on X has a coordinate 1-cocycle consisting of elements locally from $\mathcal{B}_{L,\mathcal{S},X}$). In physical terms, such as electromagnetism, for instance, the last abelian group in (4.6) classifies cohomologically the Maxwell fields, within the abstract differential geometric setup of the present paper, which involves the mentioned kind of new and enlarged singularities. More details on this, via a gauge theoretic language, and as advocated in Mallios [1], can be found in Mallios [7,8].

Remark 2

It is important to note that, just like in Mallios & Rosinger, where the nowhere dense differential algebras of generalized functions were used, also in this paper, where the space-time foam differential algebras of generalized functions are employed in the particular construction of the differential triad, there is again no need for any topological algebra structure on the local sections $B_{L,S}(U)$ of the sheaf $\mathcal{B}_{L,S,X}$. This is clearly unlike in the earlier formulations of the abstract differential geometric theory in Mallios [1-8], and it is, no doubt, rather fortunate, since it further shifts the stress to purely algebraic ideas, concepts and constructs.

One of the reasons for the lack of need of any topological algebra structure on the algebras of generalized functions under consideration is the following. It is becoming more and more clear that the classical Kuratowski-Bourbaki topological concept is not suited to the mentioned algebras of generalized functions. Indeed, these algebras prove to contain nonstandard type of elements, that is, elements which in a certain sense are infinitely small, or on the contrary, large. And in such a case, just like in the much simpler case of nonstandard reals *R, any topology which would be Hausdorff on the whole of the algebras of generalized functions, would by necessity become discrete, therefore trivial, when restricted to usual, standard smooth functions, see for details Biagioni.

Here, in order to further clarify the issue of the possible limitations of the usual Kuratowski-Bourbaki concept of topology, let us point out the following. Fundamental results from measure theory, predating the mentioned concept of topology, yet having a clear topological nature, have never been given a suitable formulation within that Kuratowski-Bourbaki concept. Indeed, such is the case, among others, with the Lebesgue dominated con-

vergence theorem, with the Lusin theorem on the approximation of measurable functions by continuous ones, and with the Egorov theorem on the relation between pointwise and uniform convergence of sequences of measurable functions.

Similar limitation of the Kuratowski-Bourbaki concept of topology appeared in the early 1950s, when attempts were made to turn the convolution of Schwartz distributions into an operation simultaneously continuous in both its arguments. More generally, it is well known that, given a locally convex topological vector space, if we consider the natural bilinear form defined on its Cartesian product with its topological dual, then there will exist a locally convex topology on this Cartesian product which will make the mentioned bilinear form simultaneously continuous in both of its variables, if and only if our original locally convex topology is in fact as particular, as being a normed space topology.

It is also well known that in the theory of ordered spaces, in particular, ordered groups or vector spaces, there are important concepts of convergence, completeness, boundedness, etc., which have never been given a suitable formulation in terms of the Kuratowski-Bourbaki concept of topology. In fact, as seen in Oberguggenberger & Rosinger, powerful general results can be obtained about the existence of generalized solutions for very large classes of nonlinear PDEs, by using order structures, and without any recourse to associated topologies.

Finally, it should be pointed out that, recently, differential calculus was given a new refoundation by using standard concepts in category theory, such as naturalness. This approach also leads to topological type processes, among them the so called toponomes or \mathcal{C} -spaces, which prove to be extensions of the usual Kuratowski-Bourbaki concept of topology, see Nel, and the references cited there.

In this way, we can conclude that mathematics contains a variety of important topological type processes which, so far, could not be formulated in convenient terms using the Kuratowski-Bourbaki topological concept. And the differential algebras of generalized functions, just as much as the far simpler nonstandard reals *R, happen to exhibit such a class of topological type processes.

Unfortunately however, there seems so far to have been insufficient awareness about the above state of affairs, a state which may be summarized as follows:

- the Kuratowski-Bourbaki concept of topology is a rather narrow particular case of the much large variety of topological type processes which have for long been used successfully in various branches of mathematics,
- important mathematical structures and developments cannot be confined within the limits of the Kuratowski-Bourbaki concept of topology,
- when using topological type structures beyond the Kuratowski-Bourbaki concept of topology sufficient care should be taken in order to follow what may indeed be the *naturally* extended concepts, thus avoiding to fall for one or another of the pet-concepts of extended topology.

A recent systematic presentation of a wide range of topological type structures, together with a number of their significant applications in Functional Analysis can be found in Beattie & Butzmann. One of the more important and useful extensions of Kuratowski-Bourbaki topology they deal with is given by the so called *continuous convergence structures*, see their Definition 1.1.5, on page 4. These topological type structures are specifically introduced in order to deal with one of the long outstanding - even if less well known - major problems in topology, namely, to define appropriate topological type structures on spaces of functions, among them, on the spaces of continuous functions $\mathcal{C}(X,Y)$, where X and Y are topological spaces. One of the main interests in dealing with that problem comes from the study of infinite dimensional manifolds, where there has been a certain awareness related to the difficulties coming from the limitation of the Kuratowski-Bourbaki concept of topology. In Kriegl & Michor, for instance, a significant effort was made in using a certain extended concept of topology, called there a convenient setting, in order to deal with infinite dimensional manifolds. As it happened however, this attempt is known not to have attained its ultimate objectives. And one possible reason for that may precisely be in the insufficiently careful, thus appropriate, or for that matter, convenient indeed, choice of the extended concept of topology they happen to use. On the other hand, the topological type processes on the nowhere dense differential algebras of generalized functions, used in Mallios & Rosinger, as well as on the space-time foam differential algebras of generalized functions employed in this paper, can be given a suitable formulation, and correspondingly, treatment, by noting that the mentioned algebras are in fact reduced powers, see Bell & Slomson, of $\mathcal{C}^{\infty}(X)$, and thus of $\mathcal{C}(X)$ as well. Let us give some further details related to this claim in the case of the space-time foam algebras. The case of the nowhere dense algebras was treated in Mallios & Rosinger.

Let us recall the definition in (2.12) of the space-time foam algebras, and note that it obviously leads to

$$(4.7) \quad B_{L,\mathcal{S}}(X) = (\mathcal{C}^{\infty}(X))^{\Lambda}/\mathcal{J}_{L,\mathcal{S}}(X) \subseteq (\mathcal{C}(X))^{\Lambda}/\mathcal{J}_{L,\mathcal{S}}(X) \subseteq$$
$$\subseteq \mathcal{C}(\Lambda \times X)/\mathcal{J}_{L,\mathcal{S}}(X)$$

assuming in the last term that on Λ we consider the discrete topology. Now it is well known, Gillman & Jerison, that the algebra structure of $\mathcal{C}(\Lambda \times X)$ is connected to the topological structure of $\Lambda \times X$, however, this connection is rather sophisticated, as essential aspects of it involve the Stone-Čech compactification $\beta(\Lambda \times X)$ of $\Lambda \times X$.

It follows that a good deal of the discourse, and in particular, the topological type one, in the space-time foam algebras $B_{L,S}(X)$ may be captured by the topology of $\Lambda \times X$, and of course, by the far more involved topology of $\beta(\Lambda \times X)$. Furthermore, the differential properties of these space-time foam algebras will, in view of (2.18), (2.20), be reducible termwise to classical differentiation of sequences of smooth functions.

In short, in the case of the mentioned differential algebras of generalized functions, owing to their structure of reduced powers, one obtains a 'two-way street'. Along it, on the one hand, the definitions and operations are applied to sequences of smooth functions, and then reduced termwise to such functions, while on the other hand, all that has to be done in a way which will be compatible with the 'reduction' of the 'power' by the quotient constructions in (2.12), or in other words, (4.7). By the way, such a 'two-way street' approach has ever since the 1950s been fundamental in the branch of mathematical logic, called model theory, see Loš. And a further quite clear and detailed illustration of its workings can be seen in the next section, in the proof of Lemma 2.

But in order not to become unduly overwhelmed by ideas of model theory, let us recall here that the classical Cauchy-Bolzano construction of the real numbers ${\bf R}$ is also a reduced power. Not to mention that a similar kind of reduced power construction - in fact, its particular case called 'ultra-power' - gives the nonstandard reals * ${\bf R}$, as well.

Remark 3

The following lines of thought stand mainly in perspective with a potential application in the problem of quantization of general relativity of the differential geometric framework that has been presented here, and whose structure sheaf of coefficients was what we have called the sheaf of spacetime foam algebras.

In this regard, by looking at the structure of the sheaf algebra $\mathcal{B}_{L,S,X}$, see section 2.5, one obtains by the definition of these algebras a decomposition of X into singular and nonsingular domains, where X is being viewed as our space-time. And as seen, both of these domains can now be *dense* in X.

What is particularly important here is that such a decomposition is obtained by means of the same structure algebra sheaf, which thus works simultaneously for both the regular and irregular parts of our space-time X. Furthermore, it is worth noting that for both parts of X, our differential geometry, in other words, the corresponding structure algebra sheaf, can equally be commutative, which may be referred to the earlier mentioned Bohr's correspondence principle. What amounts to the same, and thus pertains to the same principle, is that one is in fact not compelled at all to resort to a noncommutative structure algebra sheaf, as is traditionally done, in order to be able to cope with the 'quantum' part of X. Hence, one arrives at the mentioned principle which pertains to the description of our measurements of a quantum system, and does so simply by the differential geometric apparatus presented here, which at the end, it is but our algebra sheaf $\mathcal{B}_{L,\mathcal{S},X}$.

In this connection we further remark that one can still formulate the corresponding generalization of Einstein's equations, as this is fully explained in Mallios [7,8]. In fact, this can be done even within the so called generalized Lorentz differential triad $(X, \mathcal{A}, \partial)$, see Mallios [6]. On the other hand, we still refer to Mallios [7,8], concerning the initial formulation of the above, as well as for further pertinent comments. Other relevant argument can be found in Heller [4] and Heller & Sasin [4].

5. Appendix

Proof of Lemma 2.

It is easy to see that the restrictions in (2.37) will satisfy the required sheaf conditions. Indeed, what we actually prove here is that the family (2.37) yields a *complete presheaf*, hence, equivalently, when categorically speaking, a sheaf, see for instance, Mallios [1, chap. i, (11.37), or Theorem 13.1, and (13.18)].

We can thus turn to check whether (2.37) satisfies the first of the two conditions on complete presheaves, related to open covers, (loc.cit., p. 46, Definition 11.1).

Let us therefore look at (2.41) and take $V = \bigcup_{i \in I} V_i$, where $V_i \subseteq X$, with $i \in I$, are nonvoid open. Given now two generalized functions $T, T' \in B_{L,S|_V}(V)$, let us assume that for $i \in I$, we have

$$(5.1) T|_{V_i} = T'|_{V_i}$$

We then prove that

$$(5.2) T = T'$$

Let us note the relations

(5.3)
$$T = t + \mathcal{J}_{L,S|_{V}}(V), \quad T' = t' + \mathcal{J}_{L,S|_{V}}(V)$$

with $t, t' \in (\mathcal{C}^{\infty}(V))^{\Lambda}$, which follow from (2.12). Then (5.1) implies for $i \in I$

$$(5.4) \quad (t'-t)|_{V_i} = w_i = (w_{i(\lambda)} \mid \lambda \in \Lambda) \in \mathcal{J}_{L,\mathcal{S}|_{V_i}}(V_i)$$

Now for $i \in I$, we define the product mapping

$$(5.5) \quad \mathcal{C}_{V_i}^{\infty}(V) \times \mathcal{C}^{\infty}(V_i) \ni (\alpha, \psi) \longrightarrow \alpha \psi \in \mathcal{C}^{\infty}(V)$$

where $C_{V_i}^{\infty}(V)$ denotes the set of all smooth functions in $C^{\infty}(V)$ whose support is in V_i , while the product $\alpha\psi$ is defined by

$$(\alpha \psi)(x) = \begin{vmatrix} \alpha(x)\psi(x) & \text{if } x \in V_i \\ 0 & \text{if } x \in V \setminus V_i \end{vmatrix}$$

At this point, we consider a smooth partition of unity $(\alpha_l \mid l \in \mathbf{N})$ on V, such that, see de Rham, each α_l has a compact support contained in one of the V_i , and in addition, every point of V has a neighbourhood which

intersects only a finite number of the supports of the various α_l . In this way we obtain a mapping

(5.6)
$$N \ni l \longrightarrow i(l) \in I$$
 with supp $\alpha_l \subseteq V_{i(l)}$

Extending now termwise the above product to sequences of smooth functions indexed by $\lambda \in \Lambda$, we can define the sequence of smooth functions, see (5.4)

(5.7)
$$w = (w_{\lambda} \mid \lambda \in \Lambda) = \sum_{l \in \mathbf{N}} \alpha_l \ w_{i(l)} \in (\mathcal{C}^{\infty}(V))^{\Lambda}$$

and then show that

$$(5.8) w \in \mathcal{J}_{L,\mathcal{S}|_{V}}(V)$$

Once we have (5.8), we recall (5.4) - (5.6) and the fact that $(\alpha_l \mid l \in \mathbf{N})$ is a smooth partition of unity on V, and we obtain

$$t' - t = (\sum_{l \in \mathbf{N}} \alpha_l)(t' - t) = \sum_{l \in \mathbf{N}} \alpha_l(t' - t) = \sum_{l \in \mathbf{N}} \alpha_l(t' - t)|_{V_{i(l)}} = \sum_{l \in \mathbf{N}} \alpha_l w_{i(l)} = w$$

which in view of (5.3) will indeed yield (5.2).

In order to obtain (5.8), and due to (2.10), (2.37), it suffices to find $\Sigma \in \mathcal{S}$, for which we have

$$(5.9) w \in \mathcal{J}_{L,\Sigma \cap V}(V)$$

Let us therefore recall (5.4) and note that together with (5.5), (5.6) and (2.8), it results in

(5.10)
$$\alpha_l w_{i(l)} \in \mathcal{J}_{L,\mathcal{S}|_V}(V)$$
, for $l \in \mathbf{N}$

thus (2.10) gives a sequence of sets $\Sigma_l^V \in \mathcal{S}|_V$, with $l \in \mathbb{N}$, such that

(5.11)
$$\alpha_l w_{i(l)} \in \mathcal{J}_{L,\Sigma_l^V}(V)$$
, for $l \in \mathbf{N}$

and due to (5.10), (5.6), (2.8), we can further assume about Σ_l^V that

$$(5.12) \quad \Sigma_l^V \subseteq \text{supp } \alpha_l, \quad \text{for } l \in \mathbf{N}$$

since we can always replace in (5.11) the initial Σ_l^V with $\Sigma_l^V \cap \text{supp } \alpha_l$. However, for $l \in \mathbf{N}$, we have $\Sigma_l^V = \Sigma_l \cap V$, with suitable $\Sigma_l \in \mathcal{S}$. Then by taking

$$(5.13) \quad \Sigma = \bigcup_{l \in \mathbf{N}} \ \Sigma_l$$

and recalling (5.12), we obtain for $l \in \mathbb{N}$, $x \in V$, $\Delta \subseteq V$, Δ , neighbourhood of x, the relations

$$\Sigma_l \cap \Delta = (\Sigma_l \cap V) \cap \Delta = \Sigma_l^V \cap \Delta \subseteq \text{supp } \alpha_l \cap \Delta$$

It follows therefore from the assumed property of the supports of the partition of unity $(\alpha_l \mid l \in \mathbf{N})$, that for the given V, the sequence of singularity sets $\Sigma_l \in \mathcal{S}$, with $l \in \mathbf{N}$, satisfies condition (2.35). Thus we have $\Sigma \cap V \in \mathcal{S}|_V$. But (5.13) yields

$$\Sigma \cap V = \bigcup_{l \in \mathbf{N}} (\Sigma_l \cap V) = \bigcup_{l \in \mathbf{N}} \Sigma_l^V$$

and thus (5.7), (5.11) and (2.8) will give (5.9), and in this way, the proof of (5.8) is completed.

As a last step in order to show that (2.41) is a complete presheaf, let $T_i \in B_{L,\mathcal{S}|V_i}(V_i)$, with $i \in I$, be such that

$$(5.14) T_i|_{V_i \cap V_j} = T_j|_{V_i \cap V_j}$$

for all $i, j \in I$, for which $V_i \cap V_j \neq \phi$. Then we show that

$$\exists T \in B_{L,\mathcal{S}|_V}(V) :$$

 $(5.15) \qquad \forall \ i \in I \ :$

$$T|_{V_i} = T_i$$

Indeed, (2.12) gives the representations

(5.16)
$$T_i = t_i + \mathcal{J}_{L,\mathcal{S}|_{V_i}}(V_i), \text{ for } i \in I$$

where $t_i \in (\mathcal{C}^{\infty}(V_i))^{\Lambda}$. But then (5.14) results in

$$(5.17) (t_i - t_j)|_{V_i \cap V_j} = w_i j \in \mathcal{J}_{L, \mathcal{S}|_{V_i \cap V_i}}(V_i \cap V_j)$$

for all $i, j \in I$ such that $V_i \cap V_j \neq \phi$.

Let us take any fixed $i \in I$. Given $l \in \mathbf{N}$ such that $V_i \cap V_{i(l)} \neq \phi$, the relation (5.17) yields

$$t_{i(l)} = t_i + w_{i(l)}$$
 on $V_i \cap V_{i(l)}$

thus (5.5), (5.6) lead to

$$\alpha_l t_{i(l)} = \alpha_l t_i + \alpha_l w_{i(l)} i$$
 on V_i

But then

$$\sum_{l \in \mathbf{N}} \alpha_l \ t_{i(l)} = (\sum_{l \in \mathbf{N}} \alpha_l) t_i + \sum_{l \in \mathbf{N}} \alpha_l \ w_{i(l) i} \text{ on } V_i$$

or

$$(5.18) \quad \sum_{l \in \mathbf{N}} \alpha_l \ t_{i(l)} = t_i + \sum_{l \in \mathbf{N}} \alpha_l \ w_{i(l) \ i} \text{ on } V_i$$

On the other hand, the relation

$$(5.19) \quad (\sum_{l \in \mathbf{N}} \alpha_l \ w_{i(l) \ i})|_{V_i} \in \mathcal{J}_{L.\mathcal{S}|_{V_i}}(V_i)$$

follows by an argument similar with the one we used for obtaining (5.8) via (5.9) - (5.13). In this way, if we define

$$(5.20) T = t + \mathcal{J}_{L,\mathcal{S}|_{V}}(V) \in B_{L,\mathcal{S}_{V}}(V)$$

where

$$t = \sum_{l \in \mathbf{N}} \alpha_l \ t_{i(l)}$$

then (5.18) - (5.20) will give us (5.15), and the proof of the fact that (2.41) is a complete presheaf is completed.

We turn now to proving that (2.41) is a *fine* sheaf. This however follows easily from (2.16), which as we have noted, implies that $1_V = u(1) + \mathcal{J}_{L,\mathcal{S}|_V}(V)$ is the unit element in $B_{L,\mathcal{S}|_V}(V)$, thus the partition of unity property together with (2.8) lead to

$$1_V = \sum_{l \in \mathbf{N}} (u(\alpha_l) + \mathcal{J}_{L,\mathcal{S}|_V}(V)) \in B_{L,\mathcal{S}|_V}(V)$$

At this point, we are left only with showing that (2.41) is a flabby sheaf. Let $V' \subseteq V \subseteq X$ be nonvoid open subsets, and let $T' \in B_{L,\mathcal{S}|_{V'}}(V')$. Let us denote by Σ' the boundary of V' in V. Then clearly Σ' is closed and nowhere dense in V, while $V \setminus (V' \cup \Sigma')$ is open in V. Further, since Σ' is closed in V, there exists, Kahn, $\sigma' \in \mathcal{C}^{\infty}(V)$, such that $\Sigma' = \{ x \in V \mid \sigma'(x) = 0 \}$.

We shall use now an auxiliary function $\eta \in \mathcal{C}^{\infty}(\mathbf{R})$ such that $\eta = 1$ on $(-\infty, -1] \cup [1, \infty)$, while $\eta = 0$ on [-1/2, 1/2]. And with its help, we can define the sequence of smooth functions $\beta_l \in \mathcal{C}^{\infty}(V)$, with $l \in \mathbf{N}$, according to

(5.21)
$$\beta_l(x) = \begin{vmatrix} \eta((l+1)\sigma'(x)) & \text{if } x \in V' \cup \Sigma' \\ 0 & \text{if } x \in V \setminus (V' \cup \Sigma') \end{vmatrix}$$

It is easy to check that

(5.22) supp
$$\beta_l \subseteq V'$$
, for $l \in \mathbb{N}$ and

$$\forall K \subset \subset V'$$
:

$$\exists l \in \mathbf{N} :$$

$$(5.23) \forall k \in \mathbf{N}, \ k \ge l :$$

$$\beta_k = 1$$
 on K

Let us now assume that T' has the representation, see (2.12)

(5.24)
$$T' = t' + \mathcal{J}_{L,S|_{V'}}(V')$$

where $t' = (t'_{\lambda} \mid \lambda \in \Lambda) \in (\mathcal{C}^{\infty}(V'))^{\Lambda}$.

Then we define

$$(5.25) T = t + \mathcal{J}_{L,\mathcal{S}|_V}(V) \in B_{L,\mathcal{S}|_V}(V)$$

where $t = (t_{\lambda} \mid \lambda \in \Lambda)$ and, see (5.5), (5.22), $t_{\lambda} = \beta_{l_{\lambda}} t'_{\lambda}$, for $\lambda \in \Lambda$, $l_{\lambda} \in \mathbf{N}$ and $\lambda \leq l_{\lambda}$, this last inequality being possible, since we assumed that \mathbf{N} is cofinal in Λ .

Before going further, we have to show that the definition of T in (5.25) does not depend on the choice of t' in (5.24). Let us therefore assume that, instead of the one in (2.35), we are given another representation

$$T' = t'^* + \mathcal{J}_{L,\mathcal{S}|_{V'}}(V')$$

with $t'^* = (t'^*_{\lambda} \mid \lambda \in \Lambda) \in (\mathcal{C}^{\infty}(V'))^{\Lambda}$, then clearly

$$(5.26) t'^* - t' = (t'^*_{\lambda} - t'_{\lambda} \mid \lambda \in \Lambda) \in \mathcal{J}_{L,\mathcal{S}|_{V'}}(V')$$

As above with t in (5.25), let us now define $t^* = (t^*_{\lambda} \mid \lambda \in \Lambda) \in (\mathcal{C}^{\infty}(V))^{\Lambda}$ by $t^*_{\lambda} = \beta_{l_{\lambda}} t'^*_{\lambda}$, for $\lambda \in \Lambda$.

We show then that T in (5.25) has also the representation

$$T = t^* + \mathcal{J}_{L,\mathcal{S}|_V}(V) \in B_{L,\mathcal{S}|_V}(V)$$

or that, equivalently

$$(5.27) t^* - t \in \mathcal{J}_{L,\mathcal{S}|_V}(V)$$

Indeed, from (5.26), (2.10), (2.37) we obtain $\Sigma \in \mathcal{S}$ such that

$$t'^* - t' \in \mathcal{J}_{L,\Sigma \cap V'}(V')$$

and then (2.8) gives

$$\forall \ x \in V' \setminus (\Sigma \cap V') :$$

 $\exists \lambda \in \Lambda :$

$$(5.28) \qquad \forall \ \mu \in \Lambda, \ \mu \geq \lambda \ :$$

 $\forall p \in \mathbf{N}^n$:

$$D^p(t_{\lambda}^{\prime*} - t_{\lambda}^{\prime})(x) = 0$$

But in view of (2.42), it follows that $(\Sigma \cap V) \cup \Sigma' \in \mathcal{S}|_V$, since clearly $\Sigma' \in \mathcal{S}_{nd}(V)$. Also, clearly, we have $t_{\lambda}^* - t_{\lambda} = \beta_{l_{\lambda}}(t_{\lambda}'^* - t_{\lambda}')$, with $\lambda \in \Lambda$. And then (5.28), (5.21) and (2.8) will directly lead to

$$t^* - t \in \mathcal{J}_{L,(\Sigma \cap V) \cup \Sigma'}(V) \subseteq \mathcal{J}_{L,\mathcal{S}|_V}(V)$$

and the proof of (5.27) is completed.

At last, it follows easily from (5.21) - (5.25) that

$$T|_{V'} = T'$$

since a direct computation using also (2.8), gives

$$t'-t|_{V'}\in\mathcal{J}_{L,\phi}(V')$$

In this way the flabbiness of (2.41) is proved.

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